Recovering a linear problem from a nonlinear problem

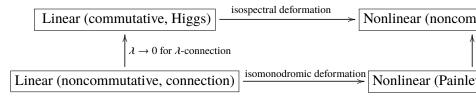
Akane Nakamura joint work with Eric Rains

Representation Theory and Integrable Systems ETH Zurich 12th August, 2019

Linear to nonlinear

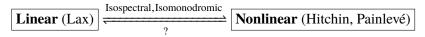
We consider the Painlevé-type equations or their autonomous (=isospectral) version, the Hitchin systems.

The direction "linear to nonlinear" is well-studied.



Jimbo-Miwa-Ueno [4], Inaba-Iwasaki-Saito [3], Rains, "Generalized Hitchin systems on rational surfaces" [13], "The birational geometry of noncommutative surfaces", [14], and more...

What if we do not know linear problem in advance, and only have nonlinear integrable systems? Can we recover a linear problem?

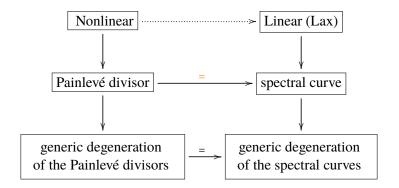


Goal

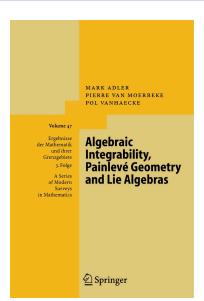
We will suggest a way to **recover a linear problem from a nonlinear problem** for the 4-dimensional autonomous Painlevé-type systems.

Summary

For the autonomous 4-dimensional Painlevé-type equations, we can recover a linear problem from a nonlinear problem (in principle).



Extracting geometrical data from nonlinear systems



Adler, Van Moerbeke, Vanhaecke, "Algebraic Integrablility, Painlevé Geometry, and Lie Algebras"[2]

- Kowalewski-Painlevé analysis
- compactification of the Liouville tori
- proving algebraic complete integrability
- etc.

Proposition 1 (Yoshida [16], Adler-van Moerbeke-Vanhake [2]) Suppose that V is a weight homogeneous vector field on \mathbb{C}^n , given by

$$\dot{x}_i = f_i(x_1, ..., x_n), \ (i = 1, ..., n)$$

and suppose that

$$x_i(t) = \sum_{k=0}^{\infty} x_i^{(k)} t^{-\nu_i + k}, \ (i = 1, \dots, n)$$

is a weight homogeneous Laurent solution for this vector field. Then the leading coefficients $x_i^{(0)}$ satisfy the non-linear algebraic equations

$$v_1 x_1^{(0)} + f_1(x_1^{(0)}, \dots, x_n^{(0)}) = 0,$$

$$\vdots$$
$$v_n x_n^{(0)} + f_n(x_1^{(0)}, \dots, x_n^{(0)}) = 0.$$

Proposition 2 (continued)

On the other hand, the subsequent terms $x_i^{(k)}$ satisfy

$$(kI_n - \mathcal{K}(x^{(0)}))x^{(k)} = R^{(k)},$$

where

$$x^{(k)} = \begin{pmatrix} x_1^{(k)} \\ \vdots \\ x_n^{(k)} \end{pmatrix}, \ R^{(k)} = \begin{pmatrix} R_1^{(k)} \\ \vdots \\ R_n^{(k)} \end{pmatrix},$$

where each $R_i^{(k)}$ is a polynomial which depends on the variables $x_1^{(l)}, \ldots, x_n^{(l)}$ with $1 \le l \le k - 1$ only. Also, the (i, j)-th entry of the $(n \times n)$ -matrix \mathcal{K} is the regular function on \mathbb{C}^n defined by

$$\mathcal{K}_{i,j} = \frac{\partial f_i}{\partial x_j} + \nu_i \delta_{i,j}.$$

The eigenvalues of \mathcal{K} are called the **Kowalevski exponents**.

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Nonlinear to linear

Example: The 2-dimensional first Painlevé equation

Let us consider the autonomous $H_{\rm I}$ given by the Hamiltonian

$$H_{\mathrm{I}}(q,p) = p^2 - q^3 - sq.$$

The Hamiltonian system is thus

$$\dot{q} = 2p \eqqcolon f_1, \quad \dot{p} = 3q^2 + s \eqqcolon f_2.$$

This is a weight-homogeneous system with the weights

deg(q,p)	$\deg(H_1,s)$
(2,3)	(6,4)

We assume the following form of formal solutions

$$q(t) = \sum_{k=0}^{\infty} x_1^{(k)} t^{-2+k}, \quad p(t) = \sum_{k=0}^{\infty} x_2^{(k)} t^{-3+k}$$

The initial terms have to satisfy the following nonlinear equations

$$2x_1^{(0)} + 2x_2^{(0)} = 0, \quad 3x_2^{(0)} + 3\left(x_1^{(0)}\right)^2 = 0.$$

These indicial equations have two solutions

$$\left(x_1^{(0)}, x_2^{(0)}\right) = (0, 0) =: m_1, (1, -1) =: m_2.$$

The subsequent terms can be computed by solving linear equations

$$\left(kI_2 - \mathcal{K}(x^{(0)})\right) \begin{pmatrix} x_1^{(k)} \\ x_2^{(k)} \end{pmatrix} = \begin{pmatrix} R_1^{(k)} \\ R_2^{(k)} \end{pmatrix},$$

where each $R_i^{(k)}$ is a polynomial which depends on the variables $x_1^{(l)}, x_2^{(l)}$ with $1 \le l \le k - 1$. Also, matrix \mathcal{K} is

$$\mathcal{K} = \begin{pmatrix} \frac{\partial f_1}{\partial q} & \frac{\partial f_1}{\partial p} \\ \frac{\partial f_2}{\partial q} & \frac{\partial f_2}{\partial p} \end{pmatrix} + \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} 0 & 2 \\ 6q & 0 \end{pmatrix} + \begin{pmatrix} 2 \\ 3 \end{pmatrix}$$

$$\left(kI_2 - \mathcal{K}(x^{(0)})\right) \begin{pmatrix} x_1^{(k)} \\ x_2^{(k)} \end{pmatrix} = \begin{pmatrix} R_1^{(k)} \\ R_2^{(k)} \end{pmatrix}$$

When the matrix $k \operatorname{Id}_n - \mathcal{K}(x^{(0)})$ is invertible, $x^{(k)}$ is uniquely determined by the preceding terms. If not, the term $x^{(k)}$ has free parameters. Therefore, the eigenvalues of $\mathcal{K}(x^{(0)})$ (the **Kowalevskaya exponents**) are important. Especially, the number of nonnegative integral Kowalevskaya exponents indicate how many parameters the series posses.

The solution starting from the initial term $m_1 = (0,0)$ is a Taylor series

$$\begin{aligned} q(t;m_1) &= \alpha + \beta t + t^2 \left(3\alpha^2 + s \right) + 2\alpha\beta t^3 + t^4 \left(3\alpha^3 + \frac{\beta^2}{2} + \alpha s \right) + O\left(t^5 \right), \\ p(t;m_1) &= \frac{\beta}{2} + t \left(3\alpha^2 + s \right) + 3\alpha\beta t^2 + t^3 \left(6\alpha^3 + \beta^2 + 2\alpha s \right) + O\left(t^4 \right). \end{aligned}$$

Since the Kowalevski exponents are 2, 3, the balance contains two free parameters α and β .

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Nonlinear to linear

The level set of the momentum map is

$$H(q(t; m_1), p(t; m_2)) = -s\alpha - \alpha^3 + \frac{\beta^2}{4} = h.$$

If we write $\alpha = x$, $\beta = 2y$, the equation is

$$y^2 = x^3 + sx + h$$

This is an elliptic curve in the Weierstrass form.

The spectral curve and the Hamiltonian for $P_{\rm I}$

• The autonomous first Painlevé equation has the following Lax pair.

$$A(x) = \begin{pmatrix} -p & x^2 + qx + q^2 + s \\ x - q & p \end{pmatrix}.$$

The spectral curve is defined by $det(yI_2 - A(x)) = 0$, which is equivalent to

$$y^2 = x^3 + sx + H_{\rm I}.$$

• The level set *H*_I(*q*, *p*) = *h* of the Hamiltonian function itself is an elliptic curve.

$$p^2 - q^3 - sq = h,$$

or by expressing p = y, q = x, we have

$$y^2 = x^3 + sx + h.$$

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The degeneration of genus 1 curve

The curve we are considering has the following form.

 $y^2 = x^3 + sx + h.$

The degeneration of this curve at $h = \infty$ can be studied in the following manner. The affine equation around $h = \infty$ is derived by transforming to $h = 1/\tilde{h}, y = \tilde{y}/\tilde{h}^3, x = \tilde{x}/\tilde{h}^2$:

$$\tilde{y}^2 = \tilde{x}^3 + s\tilde{h}^4\tilde{x} + \tilde{h}^5.$$

The discriminant and the j-invariant of the cubic are

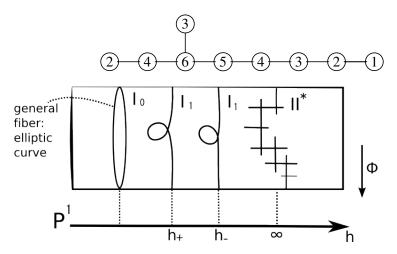
$$\begin{split} \Delta = & 4(s\tilde{h}^4)^3 + 27(\tilde{h}^5)^2 = \tilde{h}^{10}(4s^3\tilde{h}^2 + 27), \\ j = & \frac{4(s\tilde{h}^4)^3}{\Delta} = \frac{4s^4\tilde{h}^2}{4s^3\tilde{h}^2 + 27}. \end{split}$$

$$\begin{split} &\Delta = 4(s\tilde{h}^4)^3 + 27(\tilde{h}^5)^2 = \tilde{h}^{10}(4s^3\tilde{h}^2 + 27), \\ &j = \frac{4(s\tilde{h}^4)^3}{\Delta} = \frac{4s^4\tilde{h}^2}{4s^3\tilde{h}^2 + 27}. \end{split}$$

Kodaira	Dynkin	$ord(\Delta)$	$\operatorname{ord}(j)$	Kodaira	Dynkin	$ord(\Delta)$	$\operatorname{ord}(j)$
I ₀	-	0	≥0	I*	$D_4^{(1)}$	6	≥0
Im	$A_{m-1}^{(1)}$	т	<i>-m</i>	I_m^*	$D_{4+m}^{(1)}$	6 + <i>m</i>	<i>-m</i>
II	-	2	≥0	IV*	$E_{6}^{(1)}$	8	≥0
III	$A_{1}^{(1)}$	3	≥0	III*	$E_{7}^{(1)}$	9	≥0
IV	$A_{2}^{(1)}$	4	≥0	II*	$E_{8}^{(1)}$	10	≥0

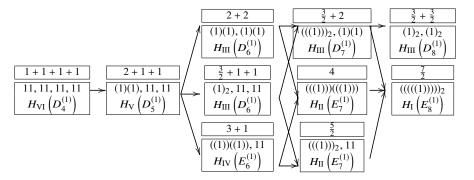
Table: Tate's algorithm and Kodaira types

At $\tilde{h} = 0$, using Tate's algorithm, we can see that the elliptic curve has the degeneration of Kodaira-type II^{*} or E_8 in Dynkin's notation.

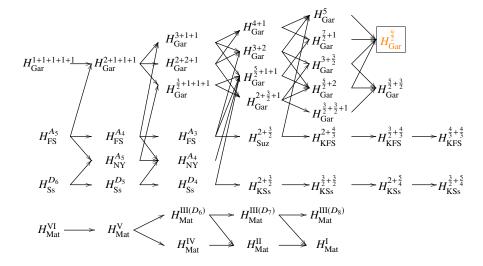


Degeneration scheme of the 2-dimensional Painlevé-type equations

There are 8 types of 2-dimensional Painlevé-type equations, and all the equations can be obtained from $H_{\rm VI}$ by degeneration.



Degeneartion scheme of the 4-dimensional Painlevé-type equations [10, 9, 15, 8, 5, 7, 6]



Example: The autonomous Garnier system of type 9/2 [12]

The autonomous Garnier system of type 9/2 is a Hamiltonian system with the Hamiltonians

$$H_{1} = H_{\text{Gar},s_{1}}^{\frac{9}{2}} = p_{1}q_{2}^{2} - p_{1}s_{1} + p_{2}s_{2} + p_{1}^{4} + 3p_{2}p_{1}^{2} + p_{2}^{2} - 2q_{1}q_{2},$$

$$H_{2} = H_{\text{Gar},s_{2}}^{\frac{9}{2}} = p_{1}^{2}q_{2}^{2} - 2p_{1}q_{1}q_{2} + p_{2}q_{2}^{2} + p_{1}^{3}s_{2} + p_{1}s_{2}^{2} + p_{2}p_{1}s_{2} + p_{2}s_{1} - p_{2}p_{1}^{3} - 2$$

$$- q_{2}^{2}s_{2} + q_{1}^{2},$$

where s_1 , s_2 are constants. The Hamiltonian system for $H_{Gar,s_1}^{\frac{9}{2}}$ is

$$\frac{dq_1}{dt} = 4p_1^3 + 6p_2p_1 + q_2^2 - s_1 =: f_1, \qquad \frac{dq_2}{dt} = 3p_1^2 + 2p_2 + s_2 =: f_3,$$

$$\frac{dp_1}{dt} = 2q_2 =: f_2, \qquad \qquad \frac{dp_2}{dt} = 2(q_1 - p_1q_2) =: f_4.$$

This is a weight-homogeneous Hamiltonian system with the following weights.

$\deg(q_1, p_1, q_2, p_2)$	$\deg(H_1,H_2,s_1,s_2)$
(5,2,3,4)	(8, 10, 6, 4)

0

There are three types of family of Laurent series, with the initial terms $m_1 = (0, 0, 0, 0), m_2 = (-1, 1, -1, 0)$ and $m_3 = (9, 3, -3, -9)$, respectively. The Kowalevski exponents (eigenvalues of $\mathcal{K}(x^{(0)})$, "K-exponents" for short) for each indicial locus is as follows.

indicial locus	K-exponents	# free para's	fiber (Liouville torus)	
$m_1 = (0, 0, 0, 0)$	(2, 3, 4, 5)	4	affine abelian surface	
$m_2 = (-1, 1, -1, 0)$	(-1, 2, 5, 8)	3	genus two curve	
$m_3 = (9, 3, -3, -9)$	(-1, -3, 8, 10)	2	point	

The following families of Laurent series starting from $m_2 = (-1, 1, -1, 0)$ contains three free parameters, α , β , and γ .

$$\begin{split} x_1(t;m_2) &= -\frac{1}{t^5} + \frac{\alpha}{t^3} + \beta + t \left(-\frac{\alpha^3}{2} - \frac{9\alpha s_2}{35} + \frac{s_1}{7} \right) - \frac{15}{2} t^2(\alpha\beta) + \gamma t^3 \\ &+ t^4 \left(\frac{18\beta s_2}{7} - \frac{15\alpha^2\beta}{2} \right) + O\left(t^5\right), \\ x_2(t;m_2) &= \frac{1}{t^2} + \frac{\alpha}{2} + t^2 \left(-\frac{3\alpha^2}{4} - \frac{3s_2}{5} \right) - 4\beta t^3 + \frac{1}{28} t^4 \left(-35\alpha^3 - 24\alpha s_2 + 4s_1 \right) + O\left(t^3\right), \\ x_3(t;m_2) &= -\frac{1}{t^3} + t \left(-\frac{3\alpha^2}{4} - \frac{3s_2}{5} \right) - 6\beta t^2 + \frac{1}{14} t^3 \left(-35\alpha^3 - 24\alpha s_2 + 4s_1 \right) - \frac{15}{2} t^2 + O\left(t^5\right), \\ x_4(t;m_2) &= -\frac{3\alpha}{2t^2} + \left(\frac{3\alpha^2}{2} + s_2 \right) + 6\beta t + t^2 \left(\frac{9\alpha^3}{8} + \frac{9\alpha s_2}{10} \right) \\ &+ \frac{3t^4 \left(1925\alpha^4 + 1680\gamma - 120\alpha^2 s_2 - 400\alpha s_1 - 1008s_2^2 \right)}{12320} + O\left(t^5\right). \end{split}$$

The level set of the moment map is

$$H_{s_1}(x_1(t;m_2), x_2(t;m_2), x_3(t;m_2), x_4(t;m_2)) = h_1,$$

$$H_{s_2}(x_1(t;m_2), x_2(t;m_2), x_3(t;m_2), x_4(t;m_2)) = h_2.$$

These are equivalent to the followings

$$\frac{405\alpha^4}{32} + \frac{81\gamma}{22} + \frac{648\alpha^2 s_2}{77} - \frac{150\alpha s_1}{77} - \frac{23s_2^2}{110} = h_1,$$

$$s_1 \left(s_2 - \frac{207\alpha^2}{308} \right) + \frac{81 \left(35 \left(99\alpha^5 + 48\alpha\gamma + 704\beta^2 \right) + 760\alpha^3 s_2 - 1008\alpha s_2^2 \right)}{24640} = h_2.$$

$$-\frac{243\alpha^3}{32} + 81\beta^2 + \frac{3\alpha h_1}{2} - \frac{81\alpha^3 s_2}{8} + s_1\left(\frac{9\alpha^2}{4} + s_2\right) - 3\alpha s_2^2 = h_2.$$

By replacing $\alpha = \frac{2}{3}x$, $\beta = \frac{1}{9}y$, the equation reads

$$y^{2} = x^{5} + 3s_{2}x^{3} - s_{1}x^{2} + (2s_{2}^{2} - h_{1})x + h_{2} - s_{1}s_{2}.$$

These three parameter family of the Laurent series corresponds to a genus two curve on a fiber of the momentum map. This curve (the boundary divisor of the Liouville torus) is called the **Painlevé divisor**.

Nakamura, Rains

Nonlinear to linear

Three types of families of Laurent solutions and restriction to a fiber

indicial locus	K-exponents	# para's	fiber (Liouville torus)	dim
$m_1 = (0,0,0,0)$	(2, 3, 4, 5)	4	affine abelian surface	4-2=2
$m_2 = (-1, 1, -1, 0)$	(-1,2,5,8)	3	genus two curve	3-2=1
$m_3 = (9,3,-3,-9)$	(-1, -3, 8, 10)	2	point	2-2=0

$$y^2 = x^5 + 3s_2x^3 - s_1x^2 + (2s_2^2 - h_1)x + h_2 - s_1s_2.$$

The three parameter Laurent solution (principal balance) corresponds to a genus two curve (Painlevé divisor) on a fiber of the momentum map.

This equation is exactly same as the spectral curve of Garnier 9/2.

$$A(x) = A_0 x^3 + A_1 x^2 + A_2 x + A_3,$$

where

$$\begin{aligned} A_0 &= \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \ A_1 &= \begin{pmatrix} 0 & p_1 \\ 1 & 0 \end{pmatrix}, A_2 &= \begin{pmatrix} q_2 & p_1^2 + p_2 + 2s_1 \\ -p_1 & -q_2 \end{pmatrix}, \\ A_3 &= \begin{pmatrix} q_1 - p_1 q_2 & p_1^3 + 2p_1 p_2 - q_2^2 + s_1 p_1 - s_2 \\ -p_2 + s_1 & -q_1 + p_1 q_2 \end{pmatrix}. \end{aligned}$$

The spectral curve

$$\det\left(yI_2 - A(x)\right) = 0.$$

of the Garnier system of type $\frac{9}{2}$ is expressed as

$$y^{2} = x^{5} + 3s_{2}x^{3} - s_{1}x^{2} + (2s_{2}^{2} - h_{1})x + h_{2} - s_{1}s_{2}.$$

The spectral curve has the exactly the same equation as the Painlevé divisor.

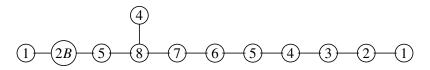
We consider the degeneration along a line $h_2 = ah_1 + b$, where *a* and *b* are generic constants.

$$y^{2} = x^{5} + 3s_{2}x^{3} - s_{1}x^{2} + (2s_{2}^{2} - h_{1})x + ah_{1} + b - s_{1}s_{2}.$$

In order to see the degeneration at $h_1 = \infty$, we introduce $\tilde{x} = x/h_1$, $\tilde{y} = y/h_1^3$, $\tilde{h} = 1/h_1$.

$$\tilde{y}^2 = \tilde{h} \left(\tilde{x}^5 + 3s_2 \tilde{h}^3 \tilde{x}^3 - s_1 \tilde{h}^4 \tilde{x} x^2 + (2s_2^2 \tilde{h} - 1) \tilde{h}^4 \tilde{x} + \tilde{h}^4 (a + (b - s_1 s_2) \tilde{h}) \right).$$

The degenerations of genus two curves can be studied using Liu's algorighm [11], which is a genus two counterpart of Tate's algorithm. VII*: $H_{Gar,s_1}^{\frac{9}{2}}$



In the examples we have seen, the **Painlevé divisor** (boundary divisor in the compactification of the Liouville torus) and the **spectral curve** are isomorphic. Therefore, they had the same generic degeneration.

Painlevé divisor	spectral curve
traceable from nonlinear system	needs an actual linear problem (Lax)

Can we recover the family of spectral curves from the family of the **Painlevé divisors?** If so, we are able to recover the singularity data of linear problem (Lax) just be looking at the nonlinear integrable system.

Nonlinear (Painlevé divisor) \rightleftharpoons **Linear** (spectral curve)

Preliminaries: Uniqueness of the polarization

The Jacobian of a smooth projective curve of genus g

 $J(C) \coloneqq H^0(\omega_C)^*/H_1(C,\mathbb{Z})$

comes with the canonical principal polarization Θ induced by the symplectic basis for *C*.

The classical Torelli's therem startes:

Theorem 1 (The classical Torelli theorem for curves)

Two Jacobians $(J(C), \Theta)$ and $(J(C'), \Theta')$ of smooth curves C and C' are isomorphic as polarized abelian varieties if and only if C and C' are isomorphic.

Therefore, it is enough to **show that** the typical element of our family has **unique principal polarization.** This in tern, is equivalent to saying that the Jacobian of the typical element of our family has **no nontrivial endomorphism**.

Theorem 2

For the 4-dimesional autonomous Painlevé-type equations, the Jacobian of generic spectral curve has **no nontrivial endomorphism**.

Using the correspondence of the NS(X) and the endomorphism ring, we have

Corolally 1

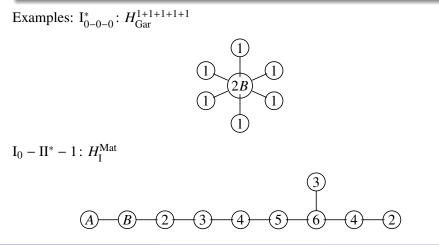
For the 4-dimesional autonomous Painlevé-type equations, the Jacobian of generic spectral curve has **unique principal polarization**.

Theorem 3

For the 4-dimesional autonomous Painlevé-type equations, the generic spectral curve is isomorphic to the corresponding Painlevé divisor. In particular, generic degeneration of the spectral curve and generic degeneration of the Painlevé divisors are the same.

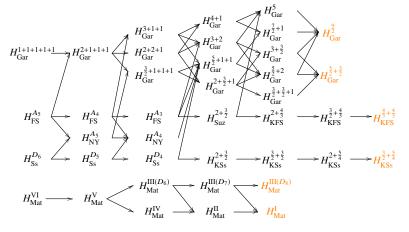
Remark 1

For the all 40 types of autonomous 4-dimensional Painlevé-type equations, the generic degeneration of the spectral curves are known [1]. Therefore, if we compute the generic degeneration of the Painlevé divisors for one of these equations, we can tell the corresponding linear equation.



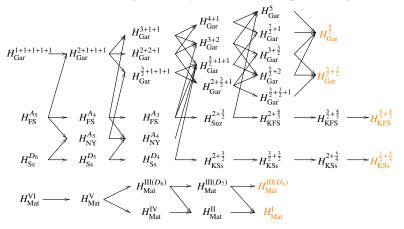
Sketch of a proof for Theorem 2

• We first prove the triviality of the endomorphism rings for the most degenerated cases ($H_{\text{Gar}}^{9/2}$, $H_{\text{Gar}}^{\frac{5}{2}+\frac{3}{2}}$, $H_{\text{KFS}}^{\frac{4}{3}+\frac{4}{3}}$, $H_{\text{KSs}}^{\frac{3}{2}+\frac{5}{4}}$, $H_{\text{Mat}}^{\text{III}(D_8)}$, $H_{\text{Mat}}^{\text{I}}$).



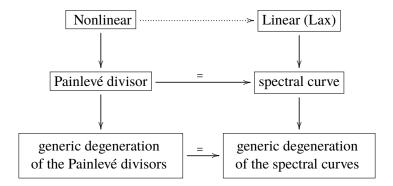
- Note that Jacobian of generic hyperelliptic curve has only trivial endomorphism.
- We will show that the space of the spectral curves of our specific system dominate the moduli space of genus two curve so that a typical curve in our family has no non-trivial endomorphisms.
- The moduli scheme of genus two curves M_2 can be identified with Proj $k[J_2, J_4, J_6, J_{10}] - \{J_{10} = 0\}$, where J_{2i} 's are the Igusa invariants and J_{10} is the discriminant.
- For the 4 cases $(H_{Gar}^{9/2}, H_{Gar}^{\frac{5}{2}+\frac{3}{2}}, H_{Mat}^{III(D_8)}, H_{Mat}^{I})$, we have checked (using Jacobian criterion) that the Igusa invariants of their spectral curves are algebraically independent, so that the each space of spectral curves dominates M_2 .
- Therefore, generic member of the spectral curves of these 4 cases has **only trivial endomorphism ring** for the Jacobian.

- For the rest 2 cases $(H_{\text{KFS}}^{\frac{4}{3}+\frac{4}{3}}, H_{\text{KSs}}^{\frac{3}{2}+\frac{5}{4}})$, the above approach does not work and our current proof is a bit more subtle (use mod *p* reduction..., we skip).
- Since we know that all the other cases degenerate to one of these 6 cases, all the cases have generically trivial endomorphism rings.



Summary

For the autonomous 4-dimensional Painlevé-type equations, We can recover a linear problem from a nonlinear problem (in principle).



Thank you for your attention!



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